

**Unit 8: Exponentials and logarithms (PURE)**

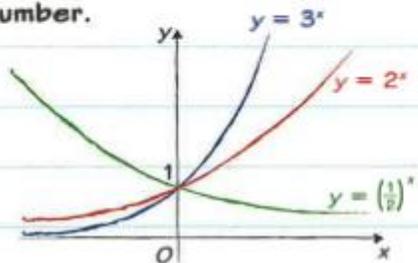
- 8a. Exponential functions and natural logarithms

**Key Vocabulary**

Exponential, exponent, power, logarithm, base, initial, rate of change, compound interest

# Exponential functions

You need to be able to sketch the graph of  $y = a^x$ . You can only sketch this graph when  $a$  is a positive number.



- $y = a^x$**
- ✓ Passes through (0, 1).
  - ✓  $y = 0$  is an asymptote.
  - ✓ If  $a > 1$  graph curves upwards.
  - ✓ If  $0 < a < 1$  graph curves downwards.

# Logarithms

Logarithms (or logs) are a way of writing facts about powers. These two statements mean the same thing:

You say 'log to the base  $a$  of  $b$  equals  $x$ '.

$$\log_a b = x \iff a^x = b$$

$a$  is the base of the logarithm.

For example:  $\log_3 9 = 2 \iff 3^2 = 9$

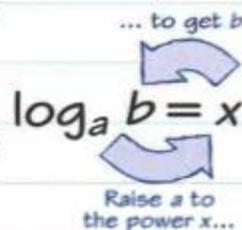
## Laws of logarithms

Learn these four key laws for manipulating expressions involving logs. These laws all work for logarithms with the same base.

- $\log_a x + \log_a y = \log_a (xy)$   
 $\log_4 8 + \log_4 2 = \log_4 16 = 2$  (since  $4^2 = 16$ )
- $\log_a x - \log_a y = \log_a \left(\frac{x}{y}\right)$   
 $\log_3 18 - \log_3 6 = \log_3 3 = \frac{1}{1}$  (since  $3^{\frac{1}{1}} = 3$ )
- $\log_a \left(\frac{1}{x}\right) = -\log_a x$   
 $\log_2 \left(\frac{1}{2}\right) = -\log_2 2 = -\frac{1}{1}$
- $\log_a (x^n) = n \log_a x$   
 $\log_5 (25^3) = 3 \log_5 25 = 3 \times 2 = 6$

## Remembering the order

The key to being confident in log questions is remembering the basic definition. Start at the base, and work in a circle.



## Undefined logs

The value  $\log_a b$  is only defined for  $b > 0$ . You can't calculate  $\log_a 0$  or the log of any negative number. If an equation contains  $\log_a x$  or  $\log_a kx$  then ignore any solutions where  $x \leq 0$ .  
If there are solutions to ignore in an exam question, you will usually be given a range of possible values for  $x$ .

If you see an equation involving logarithms in your exam, you will probably need to rearrange it using the laws of logarithms, which are covered on page 48.

# Equations with logs

## Two steps to solving log equations

Follow these two steps to solve most log equations in your exam:

- Group the log terms on one side, then use the laws of logs on page 48 to write them as a single algorithm.
- Rewrite  $\log_a f(x) = k$  as  $f(x) = a^k$  and solve the equation to find  $x$ .

**Worked example**

Express  $3 \log_2 2 + \log_2 10$  as a single logarithm (3 marks)

$$3 \log_2 2 + \log_2 10 = \log_2 (2^3) + \log_2 10$$

$$= \log_2 (2^3 \times 10)$$

$$= \log_2 80$$

Use law 4 to write  $3 \log_2 2$  as  $\log_2 (2^3)$ , then use law 1 to combine the two logarithms.

As you lower the significance level, you need more evidence to reject the null hypothesis and you lower the chance of making an incorrect conclusion.

Key point

**Unit 5b: Statistical hypothesis testing (Stats)**

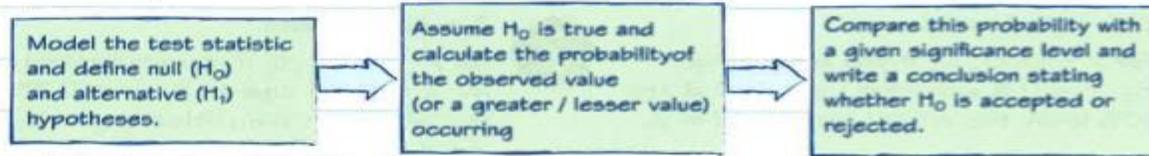
5b. Carry out hypothesis tests involving the binomial distribution

**Key Vocabulary**

. Hypotheses, significance level, one-tailed test, two-tailed test, test statistic, null hypothesis, alternative hypothesis, critical value, critical region, acceptance region, p-value, binomial model, accept, reject, sample, inference.

# Hypothesis testing

You need to be able to carry out a hypothesis test for the probability,  $p$ , in a binomial distribution. Follow these steps to carry out a hypothesis test.



The **alternative hypothesis** contradicts the null hypothesis.

Key point

It might state that the true value is greater than, less than or simply different to the value stated in the null hypothesis.

The **null hypothesis** is your starting assumption.

Key point

It states that a parameter, such as the probability, takes a certain value, and you assume this to be true in your calculations.

**Example 1**

A shop makes this claim: '85% of our customers are satisfied with our service.'

Let  $p$  be the probability that a customer, chosen at random, is satisfied.

Write the null hypothesis and the alternative hypothesis in these cases.

- a The claim is believed to be an overestimate.
- b The claim is believed to be an underestimate.
- c The claim is believed to be incorrect.

a  $H_0: p = 0.85$  and  $H_1: p < 0.85$

b  $H_0: p = 0.85$  and  $H_1: p > 0.85$

c  $H_0: p = 0.85$  and  $H_1: p \neq 0.85$

$H_1$  expresses the alternative suggestion.

If  $H_0$  is an underestimate the true value must be higher.

The true value of  $p$  could be more or less than 0.85

In a discrete distribution such as the binomial distribution, the probability of incorrectly rejecting  $H_0$  is the probability represented in the critical region and is therefore **less than or equal to** the significance level.

**Strategy**

To interpret the result of a hypothesis test

- 1 Identify the critical region and draw a diagram if it helps.
- 2 If the value from the sample lies in the critical region then you reject the null hypothesis. If the value does not lie in the critical region then you accept the null hypothesis.
- 3 End with a conclusion that relates back to the situation described in the question.

$$v = \frac{ds}{dt} \quad \text{or} \quad v = \dot{s}$$

Key point



$$a = \frac{dv}{dt} = \frac{d^2s}{dt^2} \quad \text{or} \quad a = \dot{v} = \ddot{s}$$

Key point

**Unit 9: Kinematics 2 (variable acceleration) (Mechanics)**

- 9a. Variable force; Calculus to determine rates of change for kinematics
- 9b. Use of integration for kinematics problems i.e.  $r = \int v dt$ ,  $v = \int a dt$

**Key Vocabulary**

Distance, displacement, velocity, speed, constant acceleration, variable acceleration, retardation, deceleration, gradient, area, differentiate, integrate, rate of change, straight-line motion, with respect to time, constant of integration, initial conditions.

# Variable acceleration 1

You can write displacement, velocity and acceleration as functions of time. This allows you to model the motion of an object which is moving in a straight line with variable acceleration.

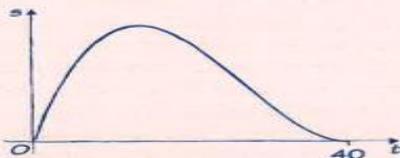
**Worked example**

A pipe-inspection robot travels along a straight section of sewer pipe. At time  $t$  minutes the distance,  $s$  metres, of the robot from its starting position is given by

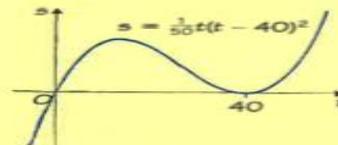
$$s = \frac{t^3 - 80t^2 + 1600t}{50}, \quad 0 \leq t \leq 40$$

(a) Sketch a distance-time graph for the motion of the robot. (3 marks)

$$s = \frac{1}{50}t(t^2 - 80t + 1600) = \frac{1}{50}t(t - 40)^2$$



You need to know more information about how the function behaves before you can sketch the distance-time graph. You can take out a factor of  $t$  and then factorise the quadratic factor. The graph of  $s = \frac{1}{50}t(t - 40)^2$  is a cubic graph with a positive coefficient of  $t^3$ . It crosses the  $t$ -axis at  $t = 0$  and touches it at  $t = 40$ :



There is more about sketching graphs of cubic functions on page 12.

The model provided is only valid for  $0 \leq t \leq 40$ . Make sure you only sketch the section of the graph for these values of  $t$ .

From your sketch you can see that  $t = 40$  represents a minimum value, so reject that solution.

**Maxima and minima**

You can use differentiation to find any maximum and minimum values of a function of time. To find the maximum value of  $s = f(t)$ , differentiate and set  $f'(t) = 0$ . Solve to find  $t$  and then substitute this value back into  $f(t)$ .

The derivative of the displacement function represents the velocity. There is more about this on the next page. There is more about differentiating and finding minima and maxima on pages 39 and 40.

**Completing the function**

An indefinite integral always produces a function with a constant of integration. You need to find this constant in order to use the function to solve numerical problems. When you integrate to find velocity or displacement, you might need to use a given value to find the constant of integration. If this is the value when  $t = 0$  it is called an initial condition.

There is more about finding functions by integrating on page 43.

(b) Find the maximum distance of the robot from its starting position. (6 marks)

$$\frac{ds}{dt} = \frac{1}{50}(3t^2 - 160t + 1600)$$

$$0 = \frac{1}{50}(3t - 40)(t - 40)$$

$$t = \frac{40}{3} \quad \text{or} \quad t = 40$$

When  $t = \frac{40}{3}$ ,

$$s = \frac{1}{50} \left( \left(\frac{40}{3}\right)^3 - 80\left(\frac{40}{3}\right)^2 + 1600\left(\frac{40}{3}\right) \right) = 189.62\dots$$

The maximum distance of the robot from its starting point is 190 m (3 s.f.)

# Variable acceleration 2

Velocity is the rate of change of displacement, and acceleration is the rate of change of velocity.

$$v = \frac{ds}{dt} \quad \text{and} \quad a = \frac{dv}{dt} = \frac{d^2s}{dt^2}$$

Integration is the inverse of differentiation, so you can integrate an expression for the velocity to find the displacement, or you can integrate an expression for the acceleration to find the velocity.

